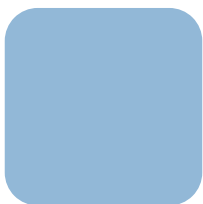


.NET on F&S Boards

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**Elektronik
Systeme**

© F&S Elektronik Systeme GmbH
Untere Waldplätze 23
D-70569 Stuttgart
Germany

Phone: +49(0)711-123722-0
Fax: +49(0)711-123722-99



About This Document

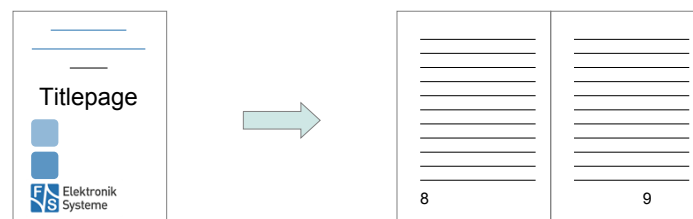
This document describes how to run .NET applications on F&S Boards.

Remark

The version number on the title page of this document is the version of the document. It is not related to the version number of any software release! The latest version of this document can always be found at <http://www.fs-net.de>.

How To Print This Document

This document is designed to be printed double-sided (front and back) on A4 paper. If you want to read it with a PDF reader program, you should use a two-page layout where the title page is an extra single page. The settings are correct if the page numbers are at the outside of the pages, even pages on the left and odd pages on the right side. If it is reversed, then the title page is handled wrongly and is part of the first double-page instead of a single page.



Typographical Conventions

We use different fonts and highlighting to emphasize the context of special terms:

File names

Menu entries

```
Board input/output
```

Program code

```
PC input/output
```

Listings

```
Generic input/output
```

Variables

History

Date	V	Platform	A,M,R	Chapter	Description	Au
2021-07-19	0.1	ALL	A	ALL	Initial version	PG
2021-07-23	0.2	ALL	M	ALL	Adapted formatting of document to F&S CI	HF
2021-07-26	0.3	ALL	A	6.3	Add VS2019 remote debugging chapter	PG
2021-07-27	0.4	ALL	M	ALL	Correct some typos, Remove false quotation marks in tasks example.	PG
2023-04-13	0.5	ALL	A,M	3,5,6	Added guide to create basic Hello World application, added command needed when installing debugger on board.	TG
2023-04-21	0.6	ALL	M	6.2	Fix pathes to match the FS-vscode-remote-debug-config Fix sshd_conf to sshd_config Add info about debugging not working on .NET7 arm	PG

V Version
A,M,R Added, Modified, Removed
Au Author

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1 Introduction

This document describes how to run .NET application to F&S-Linux boards.

Please notice, that there are no native libraries to access Linux hardware peripherals like I2C or SPI in .NET. If you need to access these in your application, please contact F&S for support to create these libraries.

This document assumes basic knowledge of using Linux on F&S boards. For a detailed introduction please see the *Linux on F&S Boards.pdf* from the document section of your F&S board at

<https://www.fs-net.de/>

2 System Requirements

The .NET images need a lot of disk space, so make sure your flash memory is big enough:

Buildroot

Image type	Image size
Ubifs Image (Nand Flash)	210 MB
Ext4 Image (eMMC)	480 MB

Yocto

Image type	Image size
Ubifs Image (Nand Flash)	
Ext4 Image (eMMC)	

3 Tested Software Versions

The Software used in this document has been tested with the following versions.

Software	Version
Development Machine	F_S_Development_Machine-Fedora_30_V2.0 F_S_Development_Machine-Fedora_35_V1.0
Buildroot fsimx6 fsimx8	fsimx6-B2021.10.1 fsimx8-B2021.06.1
Yocto	-
.NET	SDK 6.0.201 .NET Runtime 6.0.3 SDK 7.0.203 .NET Runtime 7.0.5
VSCode	1.65.2 1.77.1
VSDebugger	17.0.10413.12
Visual Studio 2019	16.10.4
VSRemoteDebugger (VS2019)	1.3

4 Compiling the .Net Images

F&S supports the build environments Buildroot and Yocto to build the system software.

This chapter describes how to build a root file system with preinstalled .NET binaries, using Buildroot or Yocto.

For a detailed description how to setup and use the build environments, please see the document *Linux on F&S Boards* chapter *Compiling the System Software*.

4.1 Prerequisites

Note

For now, we will only describe how to modify an existing build to add .NET support. If there is enough interest in this matter, we will add recipes to build .NET images fully automatic.

You can download the .NET binaries from the official Microsoft website.

Make sure to download the right OS (Linux) and architecture (Arm32 for i.MX6 and Arm64 for i.MX8 based boards).

If you want to compile the code directly on the board, you will have to download the SDK. This however needs a lot of disc space, so make sure your board has enough flash memory available.

For most cases the .NET Runtime should be sufficient.

Copy the Binaries to your development machine.

4.2 Compiling the .NET images with Buildroot

1. Get the latest F&S-Buildroot release and execute the `setup-buildroot` script to install Buildroot to your development machine. Follow the instructions.

2. Build the respective defconfig of your machine. For example run:

```
make fs<YOUR_MACHINE>_wayland_defconfig
```

in your Buildroot main directory.

3. Open the configuration menu in your buildroot directory

```
make menuconfig
```

4. Activate the ICU package at

```
Target packages -> Libraries -> Text and terminal handling ->
icu
```

5. Build buildroot

```
make -j4
```

6. Create the directory

```
output/target/usr/share/dotnet-runtime/
```

and copy the previously downloaded .NET binaries to it (the complete content of the archive).

7. Create the file

```
output/target/etc/profile.d/dotnet.sh
```

and add the following content:

```
#!/bin/sh
export PATH=$PATH:/usr/share/dotnet-runtime/
```

```
export DOTNET_ROOT=/usr/share/dotnet-runtime/
```

This will export the path to the .NET installation each time you log in.

8. Build buildroot again:

```
make -j4
```

9. The build output can be found at
output/images/

4.3 Compiling the .NET images with Yocto

TBD

5 Executing .NET applications on F&S boards

This chapter describes how to execute .NET applications on F&S boards.

5.1 Running an Application

1. Install the .NET images to your board. You will need to install kernel, device tree and root filesystem. The different ways of how to install the images are described in the document *Linux on F&S Boards* chapters Image Download and Image Storage.

2. To Create a Basic 'Hello World' Application you can use this command, which will create an Application named MyApp based on .Net 7.

```
dotnet new console -o MyApp -f net7.0
```

3. Publish your application as linux-arm for i.MX6/7 boards and linux-arm64 for i.MX8 boards. Use the *-no-self-contained* flag to exclude the runtime binaries from your build

```
dotnet publish -r linux-arm -o bin\linux-arm\publish --no-self-contained
```

4. Boot Linux and transfer your .NET application files to the board. You can transfer them via network using the tftp command or use an USB stick. See *Linux on F&S Boards* chapter *Using the Standard System and Devices*.

5. Execute the .NET applications DLL using

```
dotnet /path/to/your/application.dll
```

6 Remote debugging .NET apps on F&S Boards

You can use Visual Studio Code to program and compile your .NET applications as usual, but if you want to debug your application while running on the F&S board, some additional preparations are needed.

Note

As of this writing, remotely debugging .NET 7 apps in linux-arm environments is unreliable and may cause the process to exit prematurely. This issue is under investigation. .NET 6 apps that target linux-arm and .NET 7 apps that target linux-arm64 are unaffected.

6.1 Installing VSDebugger to the board

Download the VSDebugger

For i.MX6/7 from

<https://vsdebugger.azureedge.net/vsdbg-17-0-10413-12/vsdbg-linux-arm.tar.gz>

For i.MX8 from

<https://vsdebugger.azureedge.net/vsdbg-17-0-10413-12/vsdbg-linux-arm64.tar.gz>

Note

Remote Debugging was tested with version 17-0-10413-12. There might be a newer version available. You can test it by editing the download string.

The vsdebugger for arm needs about 104 MB of disk space.

If your board has enough flash memory you can install the VSDebugger like the dotnet Runtime binaries:

Buildroot

1. Create the directory `output/target/usr/share/dotnet-runtime/vsdbg-linux` and extract the downloaded files to it. (Make sure there is no additional sub directory)
2. Rebuild buildroot and copy the new rootfs to the board.
3. Once the Debugger is installed on the Board you will need to give the 'vsdbg' file (by default located in `/usr/share/dotnet-runtime/vsdbg-linux/`) execute Permissions. This is done with the following command:

```
chmod +x vsdbg
```

You can also copy the files to an SD card or USB stick and mount it at the board. You will have to adapt some paths later on then.

6.2 Enabling root access via SSH

VSCoDe needs root access via SSH for remote debugging.

To allow root to login via SSH with no password set, some preparations are needed.



Please note that this should only be done for development purposes!

Buildroot

1. Mount the rootfile system read-writeable

```
mount -o remount,rw /
```

2. Edit the file /etc/ssh/sshd_conf using the vi editor

```
vi /etc/ssh/sshd_config
```

3. Edit the following lines (also remove the hashes):

```
(press 'i' to enter edit mode)
#PermitRootLogin prohibit-password -> PermitRootLogin yes
#PermitEmptyPasswords no           -> PermitEmptyPasswords yes
(press 'Esc' to exit edit mode)
(type ':wq' to save and quit)
```

4. Restart the ssh daemon

```
/etc/init.d/S50sshd restart
```

5. Set an IP address on the board. You can either use DHCP running the command

```
udhcpc
```

or set it per hand with the command

```
ifconfig eth0 up <YOUR.BOARD.IP.ADDRESS>
```

You should now be able to log into root per SSH without entering a password.

6.3 Visual Studio Code

6.3.1 Configuring VSCode

In order to launch the VSDebugger on the board, you will have to create or edit the launch.json file. If it does not already exist you will be asked to create it when clicking on the *Run and Debug* tab at the side bar.

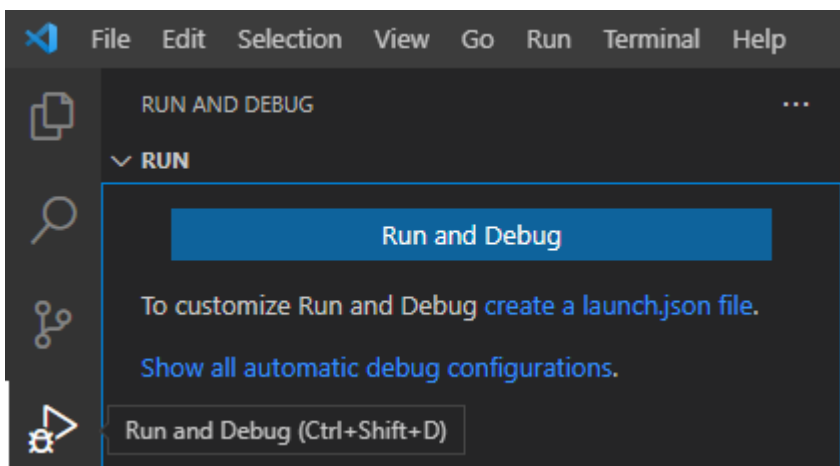


Figure 1 Creating a launch.json file

Download the FS-vscode-remote-debug-config repository from

<https://github.com/FSEmbedded/FS-vscode-remote-debug-config>

And copy/replace the files `launch.json`, `tasks.json` and `settings.json`s to the `.vscode/` directory of you project.

```
▼ .vscode
  {} launch.json
  {} settings.json
  {} tasks.json
```

Edit the following red marked lines in `settings.json`s if necessary:

- Set your board IP address here. Use `ifconfig` to show your boards IP address.

```
"FuS.boardIp": "10.0.0.103",
```

- Change this path if you installed the VSDebugger at a different location

```
"FuS.debuggerPath": "/usr/share/dotnet-runtime/vsdbg-linux/vsdbg"
```

- Change this path if you want to place your application to the flash instead of ram only (e.g to `/opt`)

```
"FuS.TargetPath": "/tmp",
```

- Change this to `arm64` for i.MX8 boards

```
"FuS.boardArch": "arm",
```

6.3.2 Start debugging in VSCode

Start debugging by clicking the Run and Debug button at the Run and Debug tab.

Your .NET application should be built, transferred to the board. The application should be started and stop, if you have set a break point.

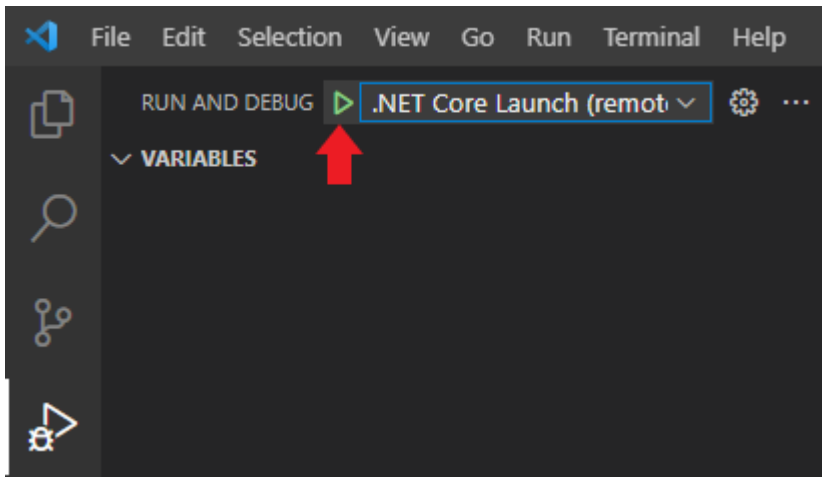


Figure 2 Start Debugging

6.4 Visual Studio 2019

There are no official solutions for remote debugging in Visual Studio 2019 yet.

You could either use Visual Studio Code to debug your application, or try community projects like

<https://github.com/radutomy/VSRemoteDebugger>

The VSRemoteDebugger needs some additional preparations to work with F&S boards.

6.4.1 Configure rootfs

Buildroot

1. Open the configuration menu in your buildroot directory

```
make menuconfig
```

2. Activate the sudo package at
Target packages -> Shell and utilities -> sudo
3. Make buildroot and install the new rootfs to the board.

6.4.2 Configure board

1. Make sure you have executed the steps *6.1 Installing VSDebugger to the board* and *6.2 Enabling root access via SSH*
2. Open a Powershell und run the following commands

```
ssh-keygen.exe -m pem  
cat ~/.ssh/id_rsa.pub | ssh root@X.X.X.X "mkdir -p ~/.ssh &&  
cat >> ~/.ssh/authorized_keys"
```

This will create a SSH private and public key and install the public key to your development board. Replace **X.X.X.X** with your boards IP address.

6.4.3 Configure VS 2019

1. Install VSRemoteDebugger at **Extensions > Manage extensions**
2. Open **Tools > Options > VSRemoteDebugger**
3. At *Local Machine Settings* set *Publish* to *True*
4. At *Remote Machine Settings* use the following settings

.NetPath	/usr/share/dotnet/dotnet
Group Name	root
IP Address	Your.board.IP.address
Project folder	/tmp/dotnet
Username	root
Visual Studio Debugger Path	/usr/share/dotnet/vsdbg-linux-arm/vsdbg

- Change *Project folder* to e.g. /opt if you don't want to debug from RAM. Make sure your system is mounted read-writeable.
 - Change Visual Studio Debugger Path if you did not install the debugger to the rootfs.
5. Set a breakpoint and run `Tools > Start Remote Debugging`. Your application should get build, transferred to the board and started for debugging.

7 Important Notice

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